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4) An Introduction to Signal Detection and Estimation, Vincent Poor, 2nd ed., 1994
5) Mathematical Methods and Algorithms for Signal Processing, Todd Moon and Wynn Stirling, 2000. Topics to be covered: Theoretical aspects of

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estimation, filtering, and detection, including most of the material in the course packet. Applications of the theory to ...

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Volume 2: Detection Theory, by Steven M. Kay, Prentice Hall 1998. Other useful references: Harry L. Van Trees, Detection, Estimation, and Modulation Theory, Part I, II, III, IV H. Vincent Poor, Introduction to Signal Detection and

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Estimation Louis L. Scharf and Cedric Demeure, Statistical Signal Processing: Detection, Estimation, and Time ...

ECE 531: Detection and Estimation Theory

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An Introduction to Signal Detection and Estimation - Second Edition Chapter IV: Selected Solutions H. V. Poor Princeton University April 26, 2005 Exercise 1:

An Introduction to Signal Detection and Estimation ...

ELE530, Detection and Estimation course taught at Princeton University.

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ELE 530: Detection and Estimation

[2] H. L. Van Trees, "Detection, Estimation, and Modulation Theory, Part I," John Wiley, 1968. Problem Sets

Problem Set 1 Solution to Problem Set 1

Problem Set 2 Solution to Problem Set 2

Problem Set 3 Solution to Problem Set 3

Problem Set 4 Solution to Problem Set 4

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Problem Set 5 Solution to Problem Set 5
Problem Set 6 Solution to Problem Set 6

EE5130 Detection and Estimation Theory

Detection, Estimation, and Modulation Theory: Part I by Harry L. Van Trees John L.

Weatherwax* April 16, 2014

Introduction Here you'll find some notes

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that I wrote up as I worked through this excellent book. I've worked hard to make these notes as good as I can, but I have no illusions that they are perfect.

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Estimation, 2nd edition, by H. Vincent Poor. The course syllabus (pdf format) including expected course outcomes, grading information, and late policies.

spinlab: The Signal Processing and Information Networking ...

Thus, the conditional risks are: $R_0(\delta, \pi_0)$
 $\tau_0^2 \int_0^3 (y+1) dy = 1$ if $0 \leq \pi_0 \leq 3$ $\tau_0^2 \int_3^7 2\tau_0^2 dy = 3$

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$3/2 + 1$ if $3/7 < \pi_0 < 3/5$ 0 if $3/7 \leq \pi_0 \leq 1$
and $R = 1 - \delta \pi_0$ $1 - \tau$ if $0 \leq \pi_0 \leq 3/7$
 $1 - \tau$ if $3/7 < \pi_0 < 3/5$ 1 if $3/7 \leq \pi_0 \leq 1$ By
inspection, a minimax threshold τ_L is
the solution to the equation $2\tau_L$

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Estimation • Kailath, Hassibi and Sayed,
Linear Estimation • Other references will

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be ...

An introduction to signal detection and estimation vincent ...

Poor does a better than average job of explaining the complicated theory behind detection and estimation. He has many examples which clarify some complicated theorems. However I find

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that too many steps are skipped.
Particularly in chapter II where the basis
for all of the detection methods become
apparent.

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Edition Author(s) : H. Vincent Poor This solution manual is not completed, just have answers for to selected problems of chapters 2, 3, 4 and 5.

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