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Solution 1.1. We will establish the three properties of a norm and then the submultiplicative property: 1.

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## **LINEAR ROBUST CONTROL SOLUTIONSMANUAL**

Offers the essentials of both robust and H<sub>∞</sub> control and is suitable for self-study. Adopts a self-contained approach, including detailed proof and development of each topic. Incorporates MATLAB tools—accompanied by step-by-step illustrations—throughout the book to execute computations. Supports discussions with numerous diagrams and figures.

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1 Essentials of Robust Control These slides will be updated when I have time. Last updated on August 28, 2000

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needed for most control systems if there were no disturbances and uncertainties.

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Robust Control 16 Basic Feedback Loop:  
 $C P F r d x_2 y v x_3 n x_1 u-x_1 = r -F x_3 x_2 = d+Cx_1 x_3 = n+Px_2 \Rightarrow 10F -C 10 0 -P 1 x_1 x_2 x_3 = r d n x_1 x_2 x_3 = 10F -C 10 0 -P 1 -1 r d n = 1 1+PCF 1 -PF -F$

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